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# Practical Electrical Engineering By Sergey N Makarov

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2 ELECTROMECHANICAL SYSTEMS ELECTROMECHANICAL SYSTEMS - VERSION 1 A relatively new branch of engineering design called mechatronics involves integrating the three areas of sensing, electronic control and mechanical actuation A modern camera is a good example of a ...

#### **Sergey G. Menabde**

Sergey G Menabde PhD Post-Doctoral Researcher Dept of Electrical Engineering, KAIST Contact information Phone +82-10-5441-1984 E-mail

menabde@kaistackr

### **Electrical and Computer Engineering Graduate Conference**

Electrical and Computer Engineering Graduate Conference May 12, 2015 Scotia Bank Auditorium McCain Arts and Social Sciences Building Halifax, NS, Canada ECEGC 2015 Annual Electrical and Computer Engineering Graduate Conference ECEGC-15, May 12, 2015, Halifax, NS, Canada ECEGC 2015 Graduate Advisor and Chair Dr Sergey Ponomarenko Conference Organizing Committee ...

### **TRANSACTIONS ON ELECTRICAL ENGINEERING**

Transactions on Electrical Engineering, Vol 5 (2016), No 3 59 TELEN2016009 DOI 1014311/TEE20163059 Modelling of High Torque Density Switched Reluctance Motors with Mutual Coupling Mario Greule 1), Johannes Müller 2) and Martin Doppelbauer 3) 1) 2) 3) Karlsruhe Institute of Technology, Karlsruhe, Germany,

### **MATHEMATICAL AND COMPUTER MODELING IN SCIENCE AND ...**

Mathematical and Computer Modeling in Science and Engineering 8 Notes on exercises • Exercises to the course are subdivided into two parts The first part includes questions and problems needed to understand theoretical concepts These questions/problems (denoted c##) are scattered throughout the text/slides It is recommended not to skip them

### **Trust Region Policy Optimization - arXiv**

Trust Region Policy Optimization John Schulman JOSCHU@EECSBERKELEYEDU Sergey Levine SLEVINE@EECSBERKELEYEDU Philipp Moritz PCMORITZ@EECSBERKELEYEDU Michael Jordan JORDAN@CSBERKELEYEDU Pieter Abbeel PABBEEL@CSBERKELEYEDU University of California, Berkeley, Department of Electrical Engineering and Computer Sciences Abstract

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### **End-to-End Training of Deep Visuomotor Policies**

End-to-End Training of Deep Visuomotor Policies Sergey Levine \*, Chelsea Finn , Trevor Darrell, Pieter Abbeel Department of Electrical Engineering and Computer Sciences, UC Berkeley fsvlevine,cbfinn,trevor,pabbeelg@eecsberkeleyedu

### **Trust Region Policy Optimization**

Trust region policy optimization, which we propose in the following section, is an approximation to Algorithm 1, which uses a constraint on the KL divergence rather than a penalty to robustly allow large updates 4 Optimization of Parameterized Policies In the previous section, we considered the policy optimiza- ),  $\uparrow$  ( $\uparrow \sim$  ( $\uparrow \sim$  old

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Learning Compound Multi-Step Controllers under Unknown Dynamics by Weiqiao Han Research Project Submitted to the Department of Electrical Engineering and Computer Sciences, University of California at Berkeley, in partial satisfaction of the requirements for the degree of Master of

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**Department of Electrical Engineering and Automation**

Aalto University School of Electrical Engineering, at a public examination held at the lecture hall TU2 of the school on 27th April 2018 at 12:00 Aalto University School of Electrical Engineering n Electrical Engineering and Automatio Information Technologies in Automation Group Department of

**Design of the Line Driver for ADSL Communication Systems ...**

Design of the Line Driver for ADSL Communication Systems by Sergey Taryshkin A thesis submitted to the Faculty of Graduate and Postdoctoral Affairs in partial fulfillment of the requirements for the degree of Master of Applied Science in Electrical and Computer Engineering Ottawa-Carleton Institute for Electrical and Computer Engineering Carleton University Ottawa, Ontario ©2011 Sergey

**Kovalenko kops eng**

Faculty of Power and Electrical Engineering Institute of Power Engineering Sergey KOVALENKO The Doctoral student of Post-graduate program „Power Engineering” Power System Static Stability Assessment Methods, Criteria and Algorithms Summary of Doctoral Thesis Scientific supervisor Dr sc ing, professor I ZICMANE Scientific advisor

**Trust Region Policy Optimization**

Sergey Levine slevine@eecsberkeleyedu Philipp Moritz pcmoritz@eecsberkeleyedu Michael Jordan jordan@csberkeleyedu Pieter Abbeel pabbeel@csberkeleyedu University of California, Berkeley, Department of Electrical Engineering and Computer Sciences Abstract In this article, we describe a method for optimizing control policies, with guaran-

**Goal-Driven Dynamics Learning via Bayesian Optimization**

Electrical Engineering and Computer Sciences at the University of California, Berkeley as the second reader of this thesis, and I am gratefully indebted to him for his very valuable comments on this thesis This work would not have been possible without Somil, Roberto, Sergey, or Claire

**Meta-Reinforcement Learning of Structured Exploration ...**

Meta-Reinforcement Learning of Structured Exploration Strategies Abhishek Gupta, Russell Mendonca, YuXuan Liu, Pieter Abbeel, Sergey Levine Department of Electrical Engineering and Computer Science